Planar Shape Deformation in X3D

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What to do for shape animation

*Objectives

- ◆ Define an animation data for a 2D shape using X3D
- ♦ By means of shape deformation
- *Assumption
 - ♦ A 2D shape consists of vertices and triangles
 - No explicit underlying structure such as skeleton



How to define the shape animation

Traditional vertex animation

- Define the positions of vertices at selected frames, and
- ♦ Interpolate the positions between two frames
 - MD2 file format by id Software in 1997
 - Consider only the animation of triangles
 - Vertex animation for approximately 10 fps
 - Limited to only predefined 20 animation sets
- Advantages
 - Easy to understand and implement
 - Easy to define any animation
- Disadvantages
 - Many selected frames due to the nonlinearity of shape animation
 - Data size due to the large amount of vertices

Suggested shape animation data

Basic strategy: using the deformation

- Split geometry and animation of the shape
- ♦ Geometry represents the topology of the shape
 - Defined by a triangle mesh
- Animation represents the shape change at all frames (or selected frames)
 - Defined by the motion of a small set of selected vertices
 - Compute the motion of other vertices at run-time
 - It requires computational cost at run-time



Suggested shape animation data

- Computing the positions of other vertices from those of selected vertices at each frame
 - Preserving some shape features of the rest pose as much as possible during the animation (as-rigid-as-possible shape animation)
 - Outline details
 - Angles of internal edges
 - Length of edges (area of triangles)
 - By nonlinear least squares optimization for
 - Laplacian coordinates of the boundary vertices
 - Mean value coordinates of the internal vertices
 - Edge length constraints of the edges
 - Slow, so requires quality control

According to the number of selected vertices

- ◆ The more vertices, the better quality
- ◆ The less vertices, the more performance
 - Cubically proportional to the number of selected vertices
 - Pre-computation time is also affected by the number of selected vertices
 - Run time is affected by the number of other vertices





When omitting pre-computation

- Preserving the mean value coordinates shows the best performance
- Preserving the edge length shows the best quality

Performance data for the dancer

- ♦ Number of vertices: 355
- ♦ Run-time: 3.162ms/frames for 10% samples

Dancer_JUMP	Sample(50%)	Sample(10%)	Sample(5%)
RMSE	0.72	4.17	4.90
Avg. difference	0.42	2.57	3.56
Max. difference	6.64	29.37	30.58



With 50% samples





Ground truth Reconstructed

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With 10% samples





Ground truth Reconstructed

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With 5% samples





Ground truth Reconstructed

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Performance data for the flower

- Number of vertices: 440
- ♦ Run-time: 4.086ms/frames for 10% samples

Flower_FLY	Sample(50%)	Sample(10%)	Sample(5%)
RMSE	0.32	1.34	2.67
Avg. difference	0.19	0.93	2.02
Max difference	3.36	9.54	11.09



With 50% samples



Ground truth Reconstructed

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With 10% samples



Ground truth Reconstructed

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With 5% samples



Shape animation data: summary



Define the motion of selected vertices

Compute the motion

of other vertices

Shape Animation Data

- Define the shape by a mesh
- Define the motion of selected vertices at every frame
- Compute the motion of other vertices at run time

Geometry

Shape

Geometry data

- Mesh information: to define shape
- Quality information: to define selected vertices

Animation data

- Frame information: to define the motion of selected vertices
- Computing information: to define the optimization method
- We can reduce the size of vertex animation by less than 1/10 with relatively small amount of errors in real time

✤Planar shape

Defines the geometry of a 2D shape

♦ A set of triangles and their vertices

PlanarShape	: X3DGeomet	tryNode {		
SFNode	[in,out]	metadata	NULL	[X3DMetadataObject]
MFVec2f	[in,out]	vertices	[]	(−∞, ∞)
MFInt32	[in,out]	faces	[]	(0, ∞)

Deformable planar shape

- Shape: vertices and faces of the shape mesh
- Control: vertices and faces of the control mesh
- Influences: relation between the shape and the control
 - Mean value coordinate can be used, then
 - It can be automatically computed from the shape and the control

DeformablePlanarShape: X3DGeometryNode {

SFNode	[in,out]	metadata	NULL	[X3DMetadataObject]
SFNode	[in,out]	shape	[]	[PlanarShape]
SFNode	[in,out]	control	[]	[PlanarShape]
MFNode	[in]	influences	[]	[Influencer]

Influencer:X3DGeometricPropertyNode {

SFNode	[in,out]	metadata
MFInt32	[in,out]	coordIndex
MFFloat	[in,out]	weights

NULL [X3DMetadataObject]
[] (0, ∞)
[] [0,1]



Vertex of shape mesh
 Vertex of control mesh
 w_i: weights w.r.t. ()

}

More controllable shape deformation

The control can also be computed using the small number of selected vertices

ConstrainedPlanarShape: X3DGeometryNode {

SFNode	[in,out]	metadata	NULL	[X3DMetadataObject]
SFNode	[in,out]	shape	[]	[PlanarShape]
SFNode	[in,out]	control	[]	[PlanarShape]
MFNode	[in]	weights	[]	[Influencer]
MFNode	[in]	constraints	[]	[PlanarShapeManipulator]





Conclusion

Representing 2D shape animation

- By means of spatial sampling
- ◆ Shape deformation is an *available* technique
- Related to geometry compression
- Future work items
 - ♦ Benefits
 - ♦ Use cases
 - Developing technical details
 - Defining the animation in X3D

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H-Anim

✤ISO/IEC H-Anim

- Define the animation of a humanoid character
- ♦ Joints and their relation
- Motion defined by either
 - Keyframing
 - Inverse Kinematics
 - Performance-based animation system
- H-Anim does not handle
 - Facial animation
- *Objectives
 - ◆ Facial animation data of H-Anim



Marker-based facial animation

Facial animation is defined by the marker positions at every frame

- Compute the displacements between an expression and the neutral expression
- Advantage
 - Reusable if the marker positions are restricted to the feature points (MPEG4)
- Disadvantage
 - The more the markers, the larger the data
 - Large error for a big expression





Reduce the size of facial animation 1

General compression technique

- Principal Component Analysis
 - Clustering the marker positions into several groups
 - Each group is embedded to a 2D space (eigenvector space)
 - At least, 1/3 data size can be removed
- Bit quantization
- Entropy encoding

Reduce the size of facial animation 2

Facial vertex animation

- ♦ As similar as the 2D shape animation data
- Define the motion of selected markers
- Compute the motion of other markers



23,728 vertices Width: 163.035 Height: 214.229 Depth: 128.017

Reduce the size of facial animation 2

Performance data

◆ Using 3D MVC, but not using any facial components

# Reconstructed	# Samples	RMSE	Max Diff.
6,294	17,434 (73%)	0.0216	0.3086
8,087	15,641 (66%)	0.0802	1.0558
12,763	10,965 (46%)	0.1339	2.6047
15,772	7,956 (33%)	0.2190	3.1428
19,482	4,246 (17%)	0.6252	11.4721

More experiments are yet required

Ground truth facial animation



From 73% samples



From 66% samples



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From 46% samples



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From 33% samples



From 17% samples



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Face component

- Defines a set of vertices
- Typically, a meaningful subset of face vertices

FaceComponent: X3DChildNode {					
SFNode	[in,out]	metadata	NULL	[X3DMetadataObject]	
SFString	[in,out]	name	\\ <i>\\</i>		
MFInt32	[in,out]	coordIndex	[]	[O, ∞)	
MFNode	[in,out]	manipulators	[]	[FaceManipulator]	

A FaceComponent is deformed by a FaceManipulator.



Face manipulator

Defines the position constraints of deformation

FaceManipul	ator: X3D	{		
SFNode	[in,out]	metadata	NULL	[X3DMetadataObject]
SFString	[in,out]	name	\\ //	
MFInt32	[in,out]	coordIndex	[]	[O, ∞)
MFVec3f	[in,out]	targetDirection	[]	(−∞, ∞)
SFFloat	[in,out]	weight	0.0	(−∞, ∞)





Action manipulator

- Defines the control information for whole facial animation
- Each manipulator can represent each component of facial expressions such as "open the left eye"

ActionManipulator: X3DGeometricPropertyNode {

SFString	[in,out]	name	\\ //	
MFInt32	[in,out]	componentIndex	[]	[0, ∞)
MFInt32	[in,out]	manipulatorIndex	[]	[0, ∞)
MFFloat	[in,out]	targetWeight	[]	(-∞, ∞)
SFFloat	[in,out]	intensity	0.0	[0, 1]

FaceManipulator node of each facial part

W=0.5

₩=0.2

W=0.2

- ActionManipulator indexing of FaceManipulator and FaceComponent
- W Weight of each FaceManipultor
- I Intensity of this action

I = 1.0

Conclusion

Representing 3D facial animation

- Select a small number of vertices,
- ◆ Define a sequence of motion of the selected vertices,
- Reconstruct the motion of other vertices using the positions of selected vertices at run time.

Future work

- How to increase benefits
- How to select a small set of vertices
- Reconcile with mpeg4 facial animation