# Planar Shape Deformation in X3D 

Jung-Ju Choi<br>Ajou University

## What to do for shape animation

\& Objectives

- Define an animation data for a 2D shape using X3D
- By means of shape deformation
*Assumption
- A 2D shape consists of vertices and triangles
- No explicit underlying structure such as skeleton



## How to define the shape animation

*Traditional vertex animation

- Define the positions of vertices at selected frames, and
$\bullet$ Interpolate the positions between two frames
- MD2 file format by id Software in 1997
- Consider only the animation of triangles
- Vertex animation for approximately 10 fps
- Limited to only predefined 20 animation sets
- Advantages
- Easy to understand and implement
- Easy to define any animation
- Disadvantages
- Many selected frames due to the nonlinearity of shape animation
- Data size due to the large amount of vertices


## Suggested shape animation data

*Basic strategy: using the deformation

- Split geometry and animation of the shape
$\diamond$ Geometry represents the topology of the shape
- Defined by a triangle mesh
- Animation represents the shape change at all frames (or selected frames)
- Defined by the motion of a small set of selected vertices
- Compute the motion of other vertices at run-time
- It requires computational cost at run-time


$$
+
$$



## Suggested shape animation data

*Computing the positions of other vertices from those of selected vertices at each frame

- Preserving some shape features of the rest pose as much as possible during the animation (as-rigid-as-possible shape animation)
- Outline details
- Angles of internal edges
- Length of edges (area of triangles)
- By nonlinear least squares optimization for
- Laplacian coordinates of the boundary vertices
- Mean value coordinates of the internal vertices
- Edge length constraints of the edges
- Slow, so requires quality control


## Quality vs. Performance

$\otimes$ According to the number of selected vertices

- The more vertices, the better quality
- The less vertices, the more performance
- Cubically proportional to the number of selected vertices
- Pre-computation time is also affected by the number of selected vertices
- Run time is affected by the number of other vertices



## Quality vs. Performance

\& When omitting pre-computation

- Preserving the mean value coordinates shows the best performance
- Preserving the edge length shows the best quality


## Quality vs. Performance

\& Performance data for the dancer

- Number of vertices: 355
- Run-time: $3.162 \mathrm{~ms} /$ frames for $10 \%$ samples

| Dancer_JUMP | Sample(50\%) | Sample(10\%) | Sample(5\%) |
| :---: | :---: | :---: | :---: |
| RMSE | 0.72 | 4.17 | 4.90 |
| Avg. difference | 0.42 | 2.57 | 3.56 |
| Max. difference | 6.64 | 29.37 | 30.58 |



## With 50\% samples



## Ground truth

Reconstructed

## With 10\% samples



Ground truth
Reconstructed

## With 5\% samples



Ground truth


Reconstructed

## Quality vs. Performance

$\otimes$ Performance data for the flower

- Number of vertices: 440
- Run-time: $4.086 \mathrm{~ms} /$ frames for $10 \%$ samples

| Flower_FLY | Sample(50\%) | Sample(10\%) | Sample(5\%) |
| :---: | :---: | :---: | :---: |
| RMSE | 0.32 | 1.34 | 2.67 |
| Avg. difference | 0.19 | 0.93 | 2.02 |
| Max difference | 3.36 | 9.54 | 11.09 |



## With 50\% samples



Ground truth


Reconstructed

## With 10\% samples



Ground truth


Reconstructed

## With 5\% samples



Ground truth


Reconstructed

## Shape animation data: summary


*Shape Animation Data

- Define the shape by a mesh
- Define the motion of selected vertices at every frame
- Compute the motion of other vertices at run time


## Shape animation data using X3D

*Geometry data

- Mesh information: to define shape
- Quality information: to define selected vertices
*Animation data
- Frame information: to define the motion of selected vertices
$\bullet$ Computing information: to define the optimization method
*We can reduce the size of vertex animation by less than $1 / 10$ with relatively small amount of errors in real time


## Shape animation data using X3D

\&Planar shape
$\bullet$ Defines the geometry of a 2D shape

- A set of triangles and their vertices

```
PlanarShape: X3DGeometryNode {
    SFNode [in,out] metadata NULI [X3DMetadataObject]
    MFVec2f [in,out] vertices [] (-\infty, \infty)
    MFInt32 [in,out] faces [] (0, \infty)
}
```


## Shape animation data using X3D

*Deformable planar shape

- Shape: vertices and faces of the shape mesh
- Control: vertices and faces of the control mesh
- Influences: relation between the shape and the control
- Mean value coordinate can be used, then
- It can be automatically computed from the shape and the control

```
DeformablePlanarShape: X3DGeometryNode
    SFNode [in,out] metadata NULL [X3DMetadataObject]
    SFNode [in,out] shape [] [PlanarShape]
    SFNode [in,out] control [] [PlanarShape]
    MFNode [in] influences [] [Influencer]
}
```


## Shape animation data using X3D

Influencer:X3DGeometricPropertyNode
SFNode [in,out] metadata MirInt32 [in,out] coordIndex MFrloat [in,out] weights

NULL [X3DMetadataObject]
[] $(0, \infty)$
[] [0,1]
\}

Vertex of shape mesh Vertex of control mesh $w_{i}$ : weights w.r.t.


## Shape animation data using X3D

*More controllable shape deformation

- The control can also be computed using the small number of selected vertices

```
ConstrainedPlanarShape: X3DGeometryNode {
    SFNode [in,out] metadata NULI [X3DMetadataObject]
    SFNode [in,out] shape [] [PlanarShape]
    SFNode [in,out] control
    MFNode [in] weights
    MFNode [in] constraints [] [PlanarShapeManipulator]
}
```


## Shape animation data using X3D

```
PlanarShapeManipulator: X3DGeometricPropertyNode {
    SFNode [in,out] metadata NULL [X3DMetadataObject]
    SFInt32 [in,out] coordIndex [] (0, \infty)
    SFFloat [in,out] targetPosition [] (-\infty, \infty)
}
```

Target position of control verticesControl vertices to be constrained
Free vertices of control mesh


## Conclusion

*Representing 2D shape animation

- By means of spatial sampling
- Shape deformation is an available technique
- Related to geometry compression
\&Future work items
- Benefits
- Use cases
- Developing technical details
- Defining the animation in X3D


# Facial Animation in X3D 

Jung-Ju Choi<br>Ajou University

## H-Anim

*ISO/IEC H-Anim

- Define the animation of a humanoid character
- Joints and their relation
- Motion defined by either
- Keyframing
- Inverse Kinematics
- Performance-based animation system
*H-Anim does not handle
- Facial animation
*Objectives
- Facial animation data of H-Anim



## Marker-based facial animation

$\star$ Facial animation is defined by the marker positions at every frame

- Compute the displacements between an expression and the neutral expression
- Advantage
- Reusable if the marker positions are restricted to the feature points (MPEG4)
$\rightarrow$ Disadvantage
- The more the markers, the larger the data
- Large error for a big expression



## Reduce the size of facial animation 1

*General compression technique

- Principal Component Analysis
- Clustering the marker positions into several groups
- Each group is embedded to a 2D space (eigenvector space)
- At least, $1 / 3$ data size can be removed
-Bit quantization
- Entropy encoding


## Reduce the size of facial animation 2

*Facial vertex animation

- As similar as the 2D shape animation data
- Define the motion of selected markers
- Compute the motion of other markers


23,728 vertices Width: 163.035 Height: 214.229 Depth: 128.017

## Reduce the size of facial animation 2

$\star$ Performance data

- Using 3D MVC, but not using any facial components

| \# Reconstructed | \# Samples | RMSE | Max Diff. |
| ---: | ---: | ---: | ---: |
| 6,294 | $17,434(73 \%)$ | 0.0216 | 0.3086 |
| 8,087 | $15,641(66 \%)$ | 0.0802 | 1.0558 |
| 12,763 | $10,965(46 \%)$ | 0.1339 | 2.6047 |
| 15,772 | $7,956(33 \%)$ | 0.2190 | 3.1428 |
| 19,482 | $4,246(17 \%)$ | 0.6252 | 11.4721 |

- More experiments are yet required


## Ground truth facial animation



## From 73\% samples



## From 66\% samples



## From 46\% samples



## From 33\% samples



## From 17\% samples



## Facial Animation using X3D

\&Face component

- Defines a set of vertices
- Typically, a meaningful subset of face vertices

| FaceComponent: X3DChildNode $\{$ |  |  |  |  |
| :--- | :--- | :--- | :--- | :--- |
| SFNode [in,out] metadata NULL | [X3DMetadataObject] |  |  |  |
| SFString | [in,out] | name | "/" |  |
| MFInt32 | $[$ in,out] | coordIndex | [] | $[0, \infty)$ |
| MFNode | [in,out] | manipulators | [] | [FaceManipulator] |
| $\}$ |  |  |  |  |

## Facial Animation using X3D

\&A FaceComponent is deformed by a FaceManipulator.


## Facial Animation using X3D

## \&Face manipulator

- Defines the position constraints of deformation

```
FaceManipulator: x3DGeometricPropertyNode {
    SFNode [in,out] metadata NULL [X3DMetadataObject]
    SFString [in,out] name
    MFInt32 [in,out] coordIndex [] [0, \infty)
    MFVec3f [in,out] targetDirection [] (-\infty, \infty)
    SFrloat [in,out] weight 0.0 (-\infty, \infty)
}
```


## Facial Animation using X3D

- Feature vertex to be moved
- Free vertex in facial part
$\rightarrow \cdots$ Target direction vector
$\longrightarrow$ Actual motion by weight(w=0.5)



## Facial Animation using X3D

\&Action manipulator

- Defines the control information for whole facial animation
- Each manipulator can represent each component of facial expressions such as "open the left eye"

```
ActionManipulator: X3DGeometricPropertyNode {
    SFString [in,out] name "/
    MFInt32 [in,out] componentIndex [] [0, \infty)
    MFInt32 [in,out] manipulatorIndex [] [0, \infty)
    MrFloat [in,out] targetWeight [] (-\infty, \infty)
    SFFloat [in,out] intensity 0.0
    [0, 1]
}
```


## Facial Animation using X3D

- 

FaceManipulator node of each facial partActionManipulator indexing of FaceManipulator and FaceComponent
W Weight of each FaceManipultor
I Intensity of this action

$$
\mathrm{I}=1.0
$$

## Conclusion

\&Representing 3D facial animation

- Select a small number of vertices,
- Define a sequence of motion of the selected vertices,
- Reconstruct the motion of other vertices using the positions of selected vertices at run time.
\&Future work
- How to increase benefits
- How to select a small set of vertices
- Reconcile with mpeg4 facial animation

